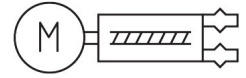


Parallel gripper kit for robots EHPS-16-A-RA50

Part number: 8210808

FESTO



 General operating condition

Data sheet

Feature	Value
Size	16
Stroke per gripper jaws	10 mm
Max. replacement accuracy	≤0.2 mm
Max. angular gripper jaw backlash ax, ay	0.4 deg
Max. gripper jaw backlash Sz	0.05 mm
Rotationally symmetrical	≤0.2 mm
Repetition accuracy, gripper	≤0.03 mm
Number of gripper jaws	2
Drive system	Electrical
Mounting position	optional
Gripper function	Parallel
Design	Worm gear unit T-shape Rack and pinion Electric gripper
Conforms to standard	IEC 61010-1
Guide	Plain-bearing guide
Position detection	Via proximity switch
Symbol	00992258
Type of motor	DC servo motor
Operator controls	Latched switch
Ready status indication	LED
Max. cycle frequency	1.1 Hz
Max. current consumption	1000 mA
Nominal operating voltage DC	24 V
Permissible voltage fluctuations	+/- 10 %
Approval	RCM trademark
KC mark	KC-EMV
CE mark (see declaration of conformity)	To EU EMC Directive In accordance with EU RoHS Directive
Corrosion resistance class CRC	1 - Low corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Sound pressure level	≤70 dB(A)
Degree of protection	IP40
Ambient temperature	5 °C ... 60 °C
Total gripping force	154 N
Mass moment of inertia	0.81 kgcm ²

Feature	Value
Max. force on gripper jaw Fz static	200 N
Max. torque at gripper Mx static	7 Nm
Max. torque at gripper My static	4.4 Nm
Max. torque at gripper Mz static	7 Nm
Lubrication interval for guide components	2 MioCyc
Product weight	400 g
Max. mass per external gripper finger	100 g
Electrical connection	5-pin Cable with plug M12x1
Type of mounting	Either: Via female thread and centring sleeve Via through-hole and centring sleeve
Note on materials	RoHS-compliant
Material housing	Anodised aluminium
Material gripper jaws	High-alloy stainless steel
Scope of delivery	1x adapter plate 1x Velcro® roll 1x position transmitter 2x connecting cables