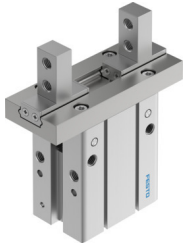


Parallel gripper DHPC-40-A-B

Part number: 8116897

FESTO



[PDF](#) General operating condition

Data sheet

Feature	Value
Size	40
Stroke per gripper jaws	15 mm
Max. replacement accuracy	0.2 mm
Max. angular gripper jaw backlash ax, ay	0 deg
Max. gripper jaw backlash Sz	0 mm
Rotationally symmetrical	≤0.2 mm
Repetition accuracy, gripper	≤0.02 mm
Number of gripper jaws	2
Drive system	Pneumatic
Mounting position	optional
Mode of operation	Double-acting
Gripper function	Parallel
Gripper force back-up	During opening
Design	Force pilot operated motion sequence
Guide	Ball guide
Position detection	Via proximity switch
Symbol	00991894
Operating pressure	0.1 MPa ... 0.8 MPa
Operating pressure	1 bar ... 8 bar
Operating pressure	14.5 psi ... 116 psi
Max. operating frequency of gripper	1 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	158 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	153 ms
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Corrosion resistance class CRC	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Ambient temperature	-10 °C ... 60 °C
Total gripping force, opening, 0.6MPa (6bar, 87 psi)	777.2 N
Total gripping force, closing, 0.6MPa (6bar, 87 psi)	717.2 N
Gripper force per gripper jaw, opening, 0.6 MPa (6 bar, 87 psi)	388.6 N
Gripper force per gripper jaw, closing, 0.6 MPa (6 bar, 87 psi)	358.6 N
Mass moment of inertia	15.49 kgcm ²
Max. force on gripper jaw Fz static	351.5 N

Feature	Value
Max. torque at gripper Mx static	16.15 Nm
Max. torque at gripper My static	9.55 Nm
Max. torque at gripper Mz static	9.55 Nm
Product weight	1408 g
Type of mounting	Either: Direct mounting via through-hole Direct mounting via thread On mounting frame Via through-hole and dowel pin Via female thread and dowel pin
Pneumatic connection	M5
Note on materials	RoHS-compliant
Material housing	Anodised aluminium
Material gripper jaws	High-alloy stainless steel