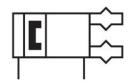
## Three-point gripper HGDT-35-A-F Part number: 560180







General operating condition

## **Data sheet**

Feature	Value
Size	35
Stroke per gripper jaws	2 mm
Max. replacement accuracy	≤0.2 mm
Max. angular gripper jaw backlash ax, ay	≤0.1 deg
Max. gripper jaw backlash Sz	≤0.05 mm
Rotationally symmetrical	≤0.2 mm
Repetition accuracy, gripper	≤0.03 mm
Number of gripper jaws	3
Mounting position	optional
Mode of operation	Double-acting Double-acting
Gripper function	3-point
Design	Force pilot operated motion sequence
Position detection	Via proximity switch
Symbol	00991894
Total gripping force, opening, 0.6MPa (6bar, 87 psi)	882 N
Total gripping force, closing, 0.6MPa (6bar, 87 psi)	822 N
Operating pressure	3 bar 8 bar
Operating pressure of blocked air	0 bar 0.5 bar
Max. operating frequency of gripper	≤4 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	43 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	39 ms
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Corrosion resistance class CRC	2 - Moderate corrosion stress
LABS (PWIS) conformity	VDMA24364-B1/B2-L
Ambient temperature	5 °C 60 °C
Gripper force per gripper jaw, opening, 0.6 MPa (6 bar, 87 psi)	294 N
Gripper force per gripper jaw, closing, 0.6 MPa (6 bar, 87 psi)	274 N
Mass moment of inertia	1.17 kgcm²
Max. force on gripper jaw Fz static	400 N
Max. torque at gripper Mx static	15 Nm
Max. torque at gripper My static	10 Nm
Max. torque at gripper Mz static	10 Nm
Lubrication interval for guide components	5 MioCyc

Feature	Value
Max. mass per external gripper finger	30 g
Product weight	307 g
Type of mounting	Either: Via through-hole and dowel pin Via female thread and dowel pin
Pneumatic connection, blocked air	M5
Pneumatic connection	M5
Note on materials	RoHS-compliant
Material cover cap	High-alloy stainless steel
Material housing	Wrought aluminium alloy Coated with COMPCOTE
Material gripper jaws	Hardened steel